

$$a_2 \frac{d^2 x}{dt^2} + a_1 \frac{dx}{dt} + a_0 x = f(t)$$

$$x = x_h + x_p$$

$$x_h \rightarrow a_2 \frac{d^2 x_h}{dt^2} + a_1 \frac{dx_h}{dt} + a_0 x_h = 0$$

$$x_p \rightarrow a_2 \frac{d^2 x_p}{dt^2} + a_1 \frac{dx_p}{dt} + a_0 x_p = f(t)$$

★ $a_1^2 > 4a_0 a_2 \rightarrow x_h = A_1 e^{s_1 t} + A_2 e^{s_2 t}$

■ $f(t) = K \rightarrow x_p = B$

$$s_1 = \frac{-a_1 - \sqrt{a_1^2 - 4a_0 a_2}}{2a_2} \quad s_2 = \frac{-a_1 + \sqrt{a_1^2 - 4a_0 a_2}}{2a_2}$$

■ $f(t) = Kt \rightarrow x_p = B_1 t + B_2$

★ $a_1^2 = 4a_0 a_2 \rightarrow x_h = A_1 e^{st} + A_2 t e^{st}$

■ $f(t) = K e^{at}$

$$s = -\frac{a_1}{2a_2}$$

◆ $a \neq s_1, a \neq s_2 \rightarrow x_p = B e^{at}$

◆ $a = s_1 \vee a = s_2; s_1 \neq s_2 \rightarrow x_p = B t e^{at}$

◆ $a = s; (s_1 = s_2 = s) \rightarrow x_p = B t^2 e^{at}$

★ $a_1^2 < 4a_0 a_2 \rightarrow x_h = e^{-\alpha t} (A_1 \cos(\omega_d t) + A_2 \sin(\omega_d t))$

$$\alpha = \frac{a_1}{2a_2} \quad \omega_d = \frac{\sqrt{4a_0 a_2 - a_1^2}}{2a_2}$$

■ $f(t) = K \sin(\omega t)$

■ $f(t) = K \cos(\omega t)$

$\rightarrow x_p = B_1 \sin(\omega t) + B_2 \cos(\omega t)$